



$$\min_{\mathbf{x}} \max_{\mathbf{t}} \mathbf{A}\mathbf{x} + \mathbf{b}$$

non-differentiable

$$\begin{array}{ll} \min_{\mathbf{x}, \mathbf{t}} & \mathbf{c} \cdot \mathbf{t} \\ \text{s.t.} & \mathbf{A}\mathbf{x} + \mathbf{b} \leq \mathbf{t} \cdot \mathbf{I} \end{array}$$

Inequality constrained

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$$\min_{\mathbf{x}, \mathbf{t}} \mathbf{c} \cdot \mathbf{t} - \sum \log(t \cdot \mathbf{I} - \mathbf{A}\mathbf{x} - \mathbf{b})$$

log-barrier

↓

$$\min_{\mathbf{x}, \mathbf{t}} f(\mathbf{x}, \mathbf{t}) = [\mathbf{c} \quad \mathbf{I}] \cdot [\mathbf{x} \quad \mathbf{t}] - \sum \log([\mathbf{-A} \quad \mathbf{I}] \cdot [\mathbf{x} \quad \mathbf{t}] - \mathbf{b})$$

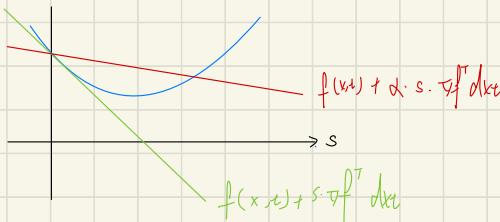
$$\nabla_{\mathbf{x}, \mathbf{t}} f(\mathbf{x}, \mathbf{t}) = [\mathbf{0} \quad \mathbf{C}] - [\mathbf{-A} \quad \mathbf{I}]^T \cdot \mathbf{I}/([\mathbf{-A} \quad \mathbf{I}] \cdot [\mathbf{x} \quad \mathbf{t}] - \mathbf{b})$$

$$\nabla_{\mathbf{x}, \mathbf{t}}^2 f(\mathbf{x}, \mathbf{t}) = [\mathbf{-A} \quad \mathbf{I}]^T \text{diag}([\mathbf{-A} \quad \mathbf{I}] \cdot [\mathbf{x} \quad \mathbf{t}] - \mathbf{b})^{-2} [\mathbf{-A} \quad \mathbf{I}]^T$$

• Solve log-barrier with Newton method

$$\nabla_{\mathbf{x}, \mathbf{t}} f(\mathbf{x} + \mathbf{d}\mathbf{x}, \mathbf{t} + \mathbf{d}\mathbf{t}) \approx \nabla_{\mathbf{x}, \mathbf{t}} f(\mathbf{x}, \mathbf{t}) + \nabla_{\mathbf{x}, \mathbf{t}}^2 f(\mathbf{x}, \mathbf{t}) \begin{bmatrix} \mathbf{d}\mathbf{x} \\ \mathbf{d}\mathbf{t} \end{bmatrix} := 0$$

$$d\mathbf{x} = \nabla_{\mathbf{x}, \mathbf{t}}^2 f(\mathbf{x}, \mathbf{t})^{-1} \cdot -\nabla_{\mathbf{x}, \mathbf{t}} f(\mathbf{x}, \mathbf{t})$$



• solve piece-wise linear with Interior-point Method

Solve log-barrier problem, the duality gap is given by m/k ($A \in \mathbb{R}^{m \times n}$)