



## Shift Theorem

1st:  $f(t) \rightarrow f(s)$

$$(T_0 f)(t) \rightarrow e^{-\pi i s t} f(s)$$

2nd:  $f(x_1, x_2) \rightarrow f(s_1, s_2)$

$$f(x_1-b_1, x_2-b_2) \rightarrow e^{-\pi i (b_1 s_1 + b_2 s_2)} T_b f \rightarrow e^{-\pi i b s} f(s)$$

$$\begin{aligned} f(T_{b_1, b_2} f)(s_1, s_2) &= \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} e^{-\pi i (x_1 s_1 + x_2 s_2)} f(x_1-b_1, x_2-b_2) dx_1 dx_2 \\ &= \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} e^{-\pi i (u_1 s_1 + u_2 (u_1 + b_1, u_2 + b_2))} f(u_1, u_2) du_1 du_2 \\ &= e^{-\pi i b s} \cdot f(s_1, s_2) \end{aligned}$$

## Stretch Theorem

1st:  $f(x) \rightarrow f(s)$

$$f(ax) \rightarrow \frac{1}{|a|} f\left(\frac{s}{a}\right)$$

2d:  $f(x, y) \rightarrow f(s_1, s_2)$

$$f(a_1 x, a_2 y) \rightarrow \frac{1}{|a_1|} \frac{1}{|a_2|} f\left(\frac{s_1}{a_1}, \frac{s_2}{a_2}\right)$$

stretching in one domain  $\rightarrow$  shrinking in the other domain still holds

$$\begin{aligned} f(T_{a_1, a_2} f)(s_1, s_2) &= \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} e^{-\pi i (s_1 u_1 + s_2 u_2)} f(a_1 x, a_2 y) dx dy \\ &= \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} e^{-\pi i \left( \frac{s_1}{a_1} u_1 + \frac{s_2}{a_2} u_2 \right)} f(u_1, u_2) \frac{1}{|a_1|} \frac{1}{|a_2|} du_1 du_2 \\ &= \frac{1}{|a_1|} \frac{1}{|a_2|} f\left(\frac{s_1}{a_1}, \frac{s_2}{a_2}\right) \quad (a \gg) \end{aligned}$$

3rd: general scaling: multiplication by matrix

$$f(x) \rightarrow f(Ax) \quad \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \rightarrow \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = Ax \quad \text{assume } \det A \neq 0$$

$$f(ax) \rightarrow \frac{1}{|\det A|} f(A^T \epsilon)$$

$$f(T_A f)(s) = \int_{\mathbb{R}^n} e^{-\pi i (x \cdot s)} f(Ax) dx \quad u = Ax$$

$$= \int_{\mathbb{R}^n} e^{-\pi i (A^T u \cdot s)} f(u) du \quad \langle Bu, y \rangle = (Bu)^T y = x^T B^T y = \langle x, B^T y \rangle$$

$$= \int_{\mathbb{R}^n} e^{-\pi i (u \cdot A^T s)} f(u) du A^T s$$

$$= \frac{1}{|\det A|} f(A^T s) \quad \text{in higher dimension, the reciprocal relationship should be understood as } A^T$$

$$\langle Ax, A^T x \rangle = x^T A^T A x = x^T x$$

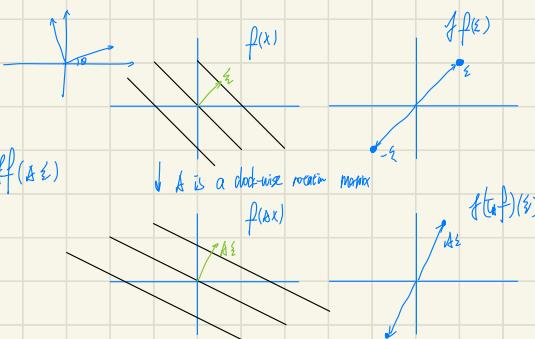
2d rotation:  $A = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix}$

$$A^T = A^{-1}$$

$$\det A = 1$$

$$(f(Ax))(t) = \frac{1}{\sqrt{t}} f(f(A^{-1}t)) = f(f(Az))$$

$$f(Ax) \rightarrow f(f(Az))$$



• Delta Functions etc

$$\langle \delta_a, \phi \rangle = \phi(a) \quad \langle \delta_b, \phi \rangle = \phi(b)$$

∴ just like 1d case

$$\begin{aligned} \langle f\delta_a, \phi \rangle &= \int \langle f\delta_a, \phi \rangle dx = \int_a^b f(x) \phi(x) dx = \phi(a) \\ \langle f\delta_b, \phi \rangle &= \int \langle f\delta_b, \phi \rangle dx = \int_b^a f(x) \phi(x) dx = \phi(b) \end{aligned}$$

$$(f \cdot \delta)(x) = f(0) \delta(x) \quad (\delta \cdot f)(x) = f(b) \delta(x)$$

$$1d: \delta(ax) = \frac{1}{|a|} \delta(x)$$

$$nd: \delta(Ax) = \frac{1}{|A|} \delta(x)$$